CLAIMS

Having thus described our invention, what we claim as new and desire to secure by Letters Patent is as follows:

1	1. A package divert mechanism, comprising:
2	a frame member adapted for use with an existing conveyor system
3	for transporting an item in an original direction; and
4	a moveable diverting mechanism extending from the frame
5	member, the moveable diverting mechanism being movable in at least one
6	direction substantially perpendicular to the original direction of travel of
7	the item being transported on the existing conveyor system.
1	2. The package divert mechanism of claim 1, wherein:
2	the moveable diverting mechanism is a bi-directional moveable
3	diverting mechanism;
4	the at least one direction is a first direction and a second opposing
5	direction, both substantially perpendicular to the original direction of
6	travel of the item; and
7	the moveable bi-directoinal diverting mechanism is capable of
8	diverting the item to either the first direction or the second opposing
9	direction.
1	3. The package divert mechanism of claim 1, wherein the
2	moveable diverting mechanism remains stationary so that a item can pass

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4. The package divert mechanism of claim 1, wherein the
moveable diverting mechanism includes adownward extending blade
having a first surface and a second surface and a longitudinal axis, the first
and second surface facing opposing directions substantially perpendicular
to the original direction of travel of the item and the longitudinal axis is
substantially parallel to the original direction of travel of the item.

- package divert mechanism of claim 1, wherein the rting mechanism further includes a moving mechanism for veable diverting mechanism.
- package divert mechanism of claim 5, wherein the moving ludes an actuator and a gliding mechanism.
- backage divert mechanism of claim 6, further comprising a of the frame and a mounting mechanism of the moveable anism, the gliding mechanism extending from the frame nnected to the mount of the moveable diverting
- 8. The package divert mechanism of claim 5, further comprising an over current sensor for determining whether a current associated with the actuator exceeds a threshold limit.
- 9. The package divert mechanism of claim 1, further comprising a plurality of sensors associated with the moveable diverting mechanism.

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	1		10. The package divert mechanism of claim 5, wherein the
	2		plurality of sensors include:
	3		at least one home sensor for detecting a home position of the
	. 4		moveable diverting mechanism;
	5		at least one over travel sensor for detecting an over travel
	6		position of the moveable diverting mechanism; and
	7		at least one photosensor for detecting a flow of the items.
:ak	1	•	11. The package divert mechanism of claim 1, further comprising
	2		momentary contacts which provide an input signal to control the
	3		movement of the moveable diverting mechanism.
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: :=3	2	A	hoods having openings, the hoods being positioned at an entrance and
	3	\mathcal{O}	each exit of the frame.
	1		13. The package divert mechanism of claim 12, further
4.º	2	, a	comprising at least one interlock switch for detecting a position of the
	3	\mathcal{O}	hoods and providing a signal to a controller for shutting down movement
	4		of the moveable diverting mechanism when any of the hoods are in an
	5		upright position.
	1		14. A bi-directional divert mechanism, comprising:
	2		a frame having an entrance and a plurality of exits:
	3	, ph	a gliding mechanism extending across a frame member of the
	4	\0 1	frame and adapted to move between opposing exits of the plurality of
	5		exits;
	6		a downward extending moveable blade member coupled to the
	7		gliding mechanism, the downward extending blade member having
	. 8		opposing blade surfaces and a longitudinal axis, the opposing blade

	9	surfaces facing opposing exits and the longitudinal axis extending in a	L
	10	direction between the entrance and another of the exits.	
	1	15. The bi-directional divert mechanism of claim 14, further	
	2	comprising a series of sensors for monitoring or controlling actions of	he
	3	downward extending moveable blade member.	
ļ-4	- 1	16. The bi-directional divert mechanism of claim 15, wherein the	ne
C.	2	series of sensors includes at least one of:	
1, 1, 1, 1, 1, 1, 1, 1, 1, 1, 1, 1, 1, 1	3	at least one home sensor for detecting a home position of the	
CII Lii	4	downward extending moveable blade member;	
John W. W. Share and Many Angle Short St.	5 ·	at least one over travel sensor for detecting an over travel posit	ion
	6	of the downward extending moveable blade member;	
marent frank fante open armen flank flank flank flank flank	7	at least one photosensor for detecting a flow of items;	
ļ.	8	an over current sensor for determining whether a current associa	ated
	9	with an actuator of the downward extending moveable blade member	
H	10	exceeds a threshold limit; and	
	11	momentary contacts which provide an input signal to control th	e .
	12 ·	movement of the downward extending moveable blade member.	
	1	17. The bi-directional divert mechanism of claim 14, further	
	2	comprising a safety hood positioned at least at one of the entrance and	
	3	exits of the frame.	
	1	18. A method of diverting an item, comprising the steps of:	
	2	locating a first home position and a second home position of a	
	3	diverting mechanism;	
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	4	positioning the diverting mechanism at one of the first home
	5	position and the second home position;
	6	determining a diverting direction of the item based on
	7	classification information associated with the item; and
	8	controlling the diverting mechanism in accordance with the
	9	diverting direction.
ļat.	1	19. The method of claim 18, wherein the controlling step includes:
	2	moving the diverting mechanism in a first direction in order to
A B grand black the track that the track the track that the track	3	divert the item in the first direction which is substantially perpendicular to
L.	4	an original direction of travel of the item;
## *#!	5	moving the diverting mechanism in a second direction opposite the
	6	first direction;
t.# ft#	7	allowing the diverting mechanism to remain stationary in order to
He track that the track that	8	allow the item to pass through unimpeded.
100 10	1	20. The method of claim 19, further comprising the step of
	2	determining and allocating a new home position of the diverting
	3	mechanism after the controlling step.
	. 1	21. The method of claim 18, further comprising the step of
	2 .	suspending movement of the diverting mechanism based on at least one
	3	of:
	4	a detection of an item being jammed;
	5	a detection of an item exceeding a threshold physical characteristic
	6	limit;
	7	a detection that the diverting mechanism exceeds a travel limit; and

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1	a detection that an operator has open access to the diverting
2	mechanism.
1	22. The method of claim 21, wherein the step of the detection of
2	the jammed item and the detection of the item exceeding a threshold
3	physical characteristic limit is based on a detection of an over current of
4	an actuator which moves the diverting mechanism.